
Retraction notice: Design and simulation of robot hand for writing and correction assistant applications

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The publishers of the *International Journal of Intelligent Unmanned Systems* wish to retract the article, Sri Naga Venkat, P., Srinath, A., Santosh Kumar, G.N., Vijay, P. and Venkatesh, R. (2022), "Design and simulation of robot hand for writing and correction assistant applications," *International Journal of Intelligent Unmanned Systems*, Vol. 10 No. 1, pp. 210-221. <https://doi.org/10.1108/IJIUS-09-2020-0058>

An internal investigation into a series of submissions has uncovered evidence that the peer review process was compromised. As a result of these concerns, the findings of the article cannot be relied upon. This decision has been taken in accordance with Emerald's publishing ethics and the COPE guidelines on retractions.

The publishers of the journal sincerely apologize to the readers.

